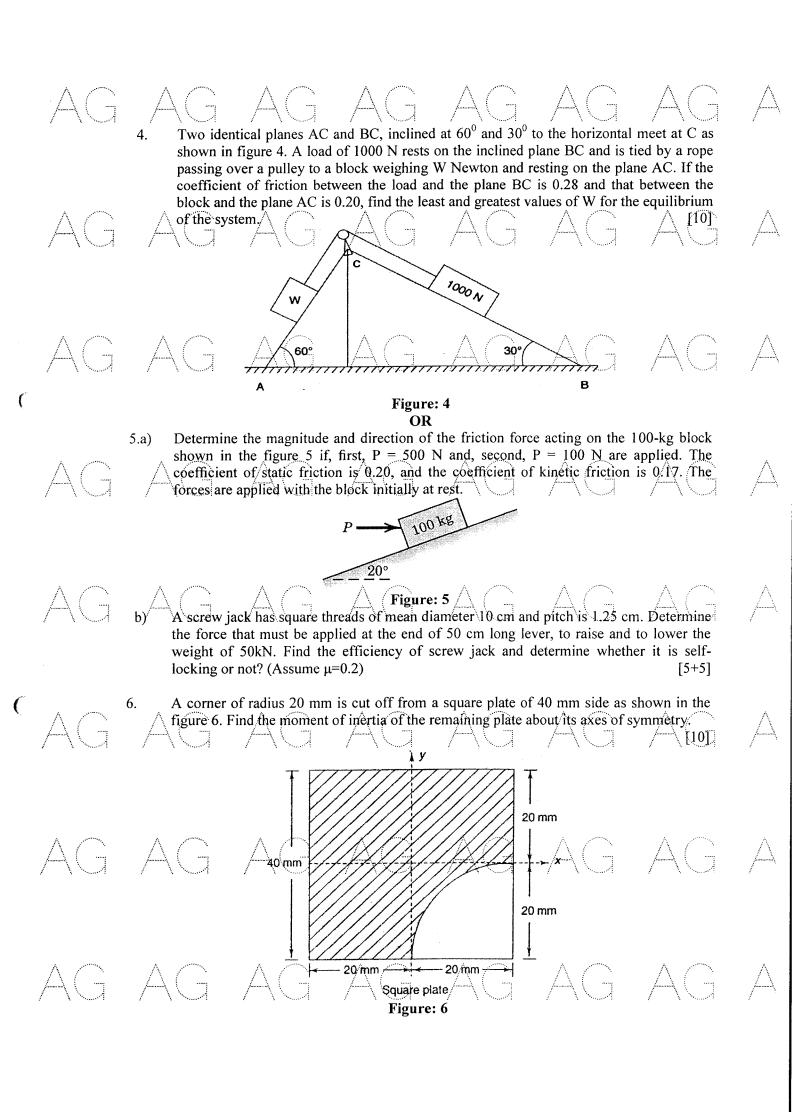
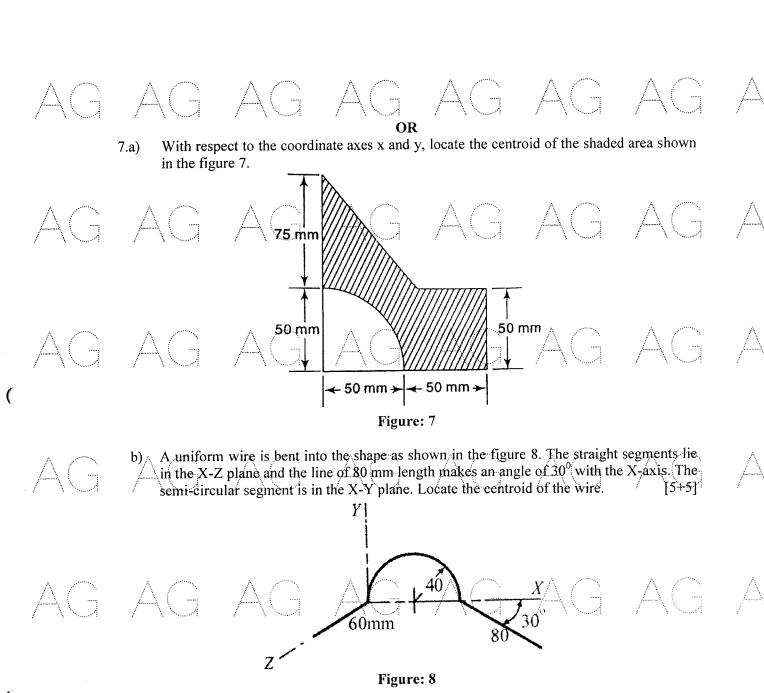
R16 Code No: 131AE JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY HYDERABAD B. Tech I Year I Semester Examinations, May - 2018 **ENGINEERING MECHANICS** (Common to CE, EEE, ME, ECE, CSE, EIE, IT, MCT, ETM, MMT, AE, MIE, PTM, CEE, MSNT) Max. Marks: 75 Time: 3 hours **Note:** This question paper contains two parts A and B. Part A is compulsory which carries 25 marks. Answer all questions in Part A. Part B consists of 5 Units. Answer any one full question from each unit. Each question carries 10 marks and may have a, b, c/as sub questions. PART-A (25 Marks) Classify different types of system of forces. [2] 1.a) The cable exerts a tension of 2 kN on the fixed bracket at A as shown in the figure 1. Write the vector expression for the tension T. 0.5 m 0.4 m 2 kN0.3 m1.2 m Figure: 1 Define the terms "coefficient of friction" and "angle of friction". [2] c) What is a wedge? Explain how the wedge is used to raise heavy loads. d) [3] [2] Write down the expression for the centroid of a quarter circle. e) [3] f) State and prove Pappus theorem I. Define mass moment of inertia of a body about an axis. g) / Determine the mass moment of inertia of a rectangular plate of size ×/"b" and [3] thickness "t" about its centroidal axes. State the D'Alembert's principle for a particle. [2] i) A force of 100 N acts on a body having a mass of 4 kg for 10 seconds. If the initial i) velocity of the body is 5 m/sec, determine the acceleration produced in the direction of force and distance moved by the body in 10 seconds.

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8.a) Determine the mass moment of inertia of a uniform ring having radius 'R' and thickness

b) Determine the mass moment of inertia of a solid cone of height 'h' and base radius 'r' about its axis of rotation.

[5+5]

9. A right circular cone made of steel has a height of 500 mm and a base diameter of 600 mm. A hole 150 mm deep and 200 mm diameter is drilled from the centre of the base of the cone and filled with lead. Lead weighs 11400 kg/m³ and steel weighs 7860 kg/m³. Determine the mass moment of inertia of the resulting solid with respect to its geometrical axis.

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